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Control / Regulation

Brinkmann coolant pumps with frequency converter 1.3 – 22 kW

Pumps with integrated frequency converter offer the optimum supplement to the existing product line for your application

With the use of a frequency converter the Q/H curve which is typical for centrifugal pumps, is replaced by a performance curve array. This makes it possible to regulate the pump to various operating points within the performance curve array, allowing the pump to be optimally matched to your specific application.

Pump Regulation

Regulation is an operation with which a physical value such as pressure is continuously measured and compared with a set value. In the event of deviation the regulation device (here a PI controller) provides for the desired adaptation.

With regulation a check is made whether a desired state is achieved or not. This allows a previously set pressure to be held constant within certain ranges in a process regardless of the flow quantities supplied.

Pump control

Control is an operation in which a physical value such as pressure or flow rate is influenced by other values.

Within pump control we also speak of an open effective circuit, because the effect of the control is not monitored. Interferences occurring in the system cannot be compensated, because the output value has no effect on the input value.

Pumps with integrated frequency converter are always supplied preprogrammed by the manufacturer.



Monitoring and feedback of output value

e. g. pressure or fill level (0/4 - 20 mA o. 0 - 10 V)

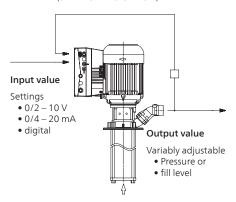


Fig. 2: Scheme of regulation

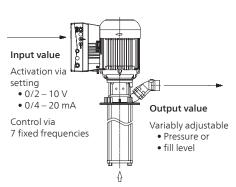


Fig. 4: Control scheme

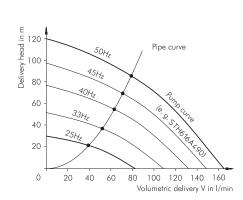


Fig. 1: Performance map

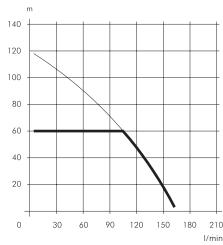


Fig. 3: Pressure regulation limited to max. 6 bar

Control / Regulation



1. Pump control via analog signal

When the coolant pump is controlled by using a frequency converter, nearly an infinite number of pressures can be achieved, for example, for different tools.

Usually the layout of the pump is limited to the 50 Hz version. Operation at higher frequencies is possible for various pumps with power reserves after consulting with the company.

The frequency converter is then operated at the current limit. This means the motor is operated at the set motor current rating at its maximum. If the pump requires more motor power for the operating point, the frequency is reduced until the max. motor current is reached again.

2. Pump control via fixed frequencies (max. 7)

An alternative to analog pump control is digital control of the frequency converter over 3 digital inputs. Here up to 7 different fixed frequencies can be set.

With fixed frequency control it is possible to realize different pressure stages with one tool.

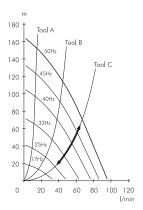


Fig. 5: Analog signal (infinite)

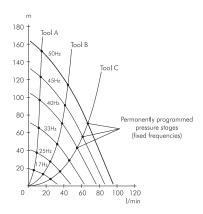


Fig. 6: Fixed frequencies

Technical Information

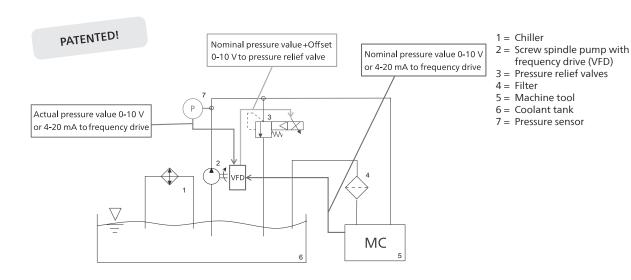


Control / Regulation

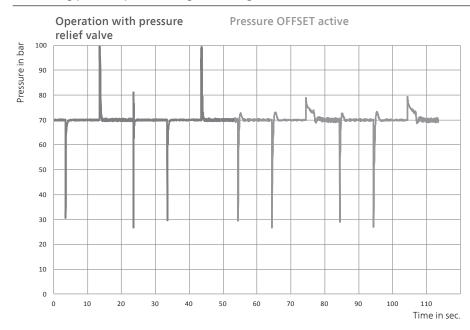
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Brinkmann Pumps Offset Regulation for High Pressure Pumps

The target pressure is calculated by the VFD based on the working point and is not supplied by the machine tool. The intelligent control of the valves allows for minimizing potential pressure spikes.



Minimizing pressure peaks during tool change



Technical Information

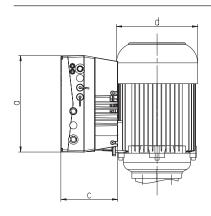


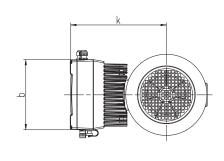
Control / Regulation



| TECHNICAL DATA Frequency converter FKO (1.5 – 22 kW) | | | | | | | | | |
|--|--|------------|--------------|------------|--|--|--|--|--|
| Function | Specification | | | | | | | | |
| Rated voltage | 3 AC 380 V -10 % 480 V +10 % | | | | | | | | |
| Rated frequency | 50/60 Hz ± 6 % | | | | | | | | |
| Output ranges | 1.5 kW | 2.2 – 4 kW | 5.5 – 7.5 kW | 11 – 22 kW | | | | | |
| Housing size | А | В | С | D | | | | | |
| Protective system | IP 65 IP 55 | | | | | | | | |
| EMV approvals acc. to EN61800-3US | C2 | | | | | | | | |
| Temperature range | −10 °C +50 °C | | | | | | | | |
| Overload capability | 1.5 times rated output current | | | | | | | | |
| Protective functions | undervoltage, overvoltage, l ² t-restriction, short circuit, motor temperature, converter temperature, anti-tilt protection | | | | | | | | |
| Output frequency range | according to layout at factory | | | | | | | | |
| Digital inputs | 4 | | | | | | | | |
| Fixed frequencies | 7 | | | | | | | | |
| Digital outputs | 2 | | | | | | | | |
| Analog inputs | 2 analog inputs (0/2 – 10 V, 0/4 – 20 mA) | | | | | | | | |
| Analog outputs | $0-10$ V (-Imax = 10 mA) or $0-20$ mA (burden R = 500 Ω) | | | | | | | | |
| Process control | PID | | | | | | | | |
| Relay outputs | 2 x NO contacts 250 V AC 2 A | | | | | | | | |
| USB interface | USB on plug M12 (RS485/RS232) | | | | | | | | |
| Manual control unit (optional) | MMI with cable | | | | | | | | |
| Bus modules (optional) | CANopen, EtherCAT, PROFINET | | | | | | | | |
| UL approval | yes | | | | | | | | |

Dimensions with Brinkmann motor





| Motor power kW | housing size | a mm | b mm | c mm | d mm | k mm |
|-------------------|--------------|---------|---------|---------|---------|---------|
| 1.1 | А | 233 | 153 | 120 | 138 | 199 |
| 1.3 – 1.7 | А | 233 | 153 | 120 | 176 | 209 |
| 1.9 – 2.6 | В | 270 | 189 | 140 | 176 | 223 |
| 3.0 – 4.0 | В | 270 | 189 | 140 | 218 | 243 |
| 5.0 – 5.5 | С | 307 | 223 | 181 | 218 | 287 |
| 6.0 – 9.0 | С | 307 | 223 | 181 | 258 | 306 |
| 11.0 – 13.0 | D | 414 | 294 | 233 | 314 | 404 |